

#### STEP 1 – ASSESSMENT DETAILS

| Method Statement Reference:            | CCRM-084                     | FREQUENCY (TICK AS APPROPRIATE) |                                       |         |           |        |  |
|--|------------------------------|---------------------------------|---------------------------------------|---------|-----------|--------|--|
| Issue Number                           | 01                           | Daily                           | Weekly                                | Monthly | Quarterly | Ad Hoc |  |
| Task:                                  | Using a Pudu SH1             | - Daily                         |                                       |         |           |        |  |
| Date Completed:                        | 24 September 2025            |                                 |                                       |         |           |        |  |
| Employee consultation and involvement: | Dina Oliveira                | ✓                               |                                       |         |           |        |  |
| Re-Assessment Due*:                    | One year from the above date |                                 |                                       |         |           |        |  |
| Method Statement Completed By:         | Health & Safety Manager      |                                 | Telephone Number:<br>6330 / 111 / 999 |         |           |        |  |

STEP 2 – PERSONNEL REQUIRED (DURING ACTIVITY)

| Lone Worker | 2 or More Persons | First Aider | Supervisor/Team Leader | Management |
|-------------|-------------------|-------------|------------------------|------------|
| ✓           |                   |             | ✓                      |            |

### STEP 3 – PROCEDURES TO BE CARRIED OUT (BEFORE STARTING WORK)

| Read the<br>appliance's<br>user manual | Training and Knowledge Company safety Site -induction form: F039 | Perform a<br>Visual safety<br>check of the<br>equipment | Assess the footfall of the area | Fit Other safety<br>control<br>implemented by us<br>or the client | Check for visual<br>damage | Place<br>Warning<br>Signs | Surface<br>preparation/<br>remove loose<br>items | Check the<br>machine is<br>charged for<br>use | Check the<br>area to be<br>cleaned for<br>obstacles |
|--|--|---|---------------------------------|---|----------------------------|---------------------------|--|---|---|
| ✓                                      | √  | ✓   | ✓                               | ✓   | ✓                          | ✓                         | ✓  | ✓   | ✓   |

### STEP 4 – HAZARDS, PRODUCT AND PPE

| Slips, Trips & Falls | Electric Shock | Fire Risk | Manual Handling | Harmful/Irritant | Eye Protection | Rubber Gloves | Sensible Work<br>Shoes |
|----------------------|----------------|-----------|-----------------|------------------|----------------|---------------|------------------------|
| <u>As</u>            | 4              |           | 7=              | <u>(!)</u>       |                |               | 3                      |
| ✓                    | ✓              | ✓         | ✓               |                  |                |               | ✓                      |

### STEP 5 - PRODUCT USAGE - DO NOT USE CHEMICALS INSIDE THE ROBOT

| Product Name | Product Usage | Product Type | Usage Dilution | Application / Equipment |
|--------------|---------------|--------------|----------------|-------------------------|
| NA           | NA            | NA           | NA             | Pudu SH1                |



#### STEP 6 – METHOD STATEMENT

| 2167 0    | - METHOD STATEMENT   | LIETUOD                     | CARE OF FOLUDATE IT                |
|-----------|--|-----------------------------|------------------------------------|
|           | SAFETY   | METHOD                      | CARE OF EQUIPMENT                  |
|           |  |                             |                                    |
| 1.        | Untrained operatives operating the device are prohibited.  | METHOD                      | 1. Only attempt maintenance of     |
| 2.        | Put warning signs before commencing the task   |                             | the Pudu SH1 if you have been      |
| 3.        | Work to be undertaken only after visual safety check has been carried out  | 1.Make sure Work            | fully trained to do so.            |
| 4.        | Do not rest the device body against other objects or walls when the device is in working position, after the task is | area is clear for safe      | 2. Do not clean or maintain the    |
|           | finished, adjust the device to the store position and store it on a flat ground.                                     | access and                  | device when it is powered on       |
| 5.        | Clean up any large particles of rubbish on the ground before use to avoid motor overload.                            | operation                   | and working.                       |
| 6.        | Device can only be used on indoor and outdoor flat ground, avoiding bumpy surfaces such as steps.                    | 2.Do not try and            | 3. Check the device before use.    |
| 7.        | Do not add flammable, strong acid or alkaline detergents that may be harmful to the device or personnel to the       | move robot                  | 4. Do not replace the disc brush   |
|           | solution tank.   | manually                    | and squeegee when the device       |
| 8.        | Do not use the robot at a temperature above 40°C or below 1°C.   | 3.Inspect the access        | is working.                        |
| 9.        | Keep away from flammable dust, liquid, or vapor when operating the device.   | way route for the           | 5. Do not use any water            |
| 10.       | Do not leave the device on ramps or slopes as the device may flip. Leave the device on a flat, hard surface          | robot and remove            | pressure cleaner to clean the      |
|           | Do not push the robot backward when the power is on.   | loose items such as         | device directly.                   |
|           | Do not expose the charger to rain;   | clothing or large           | 6. Do not immerse the              |
|           | Do not use Pudu SH1 on electrical sockets on the floor to avoid electric shocks;                                     | items of rubbish.           | equipment in water                 |
|           | Do not climb over Pudu SH I  | 4. Carry on the visual      |                                    |
| 15.       | Do not use/leave Pudu SH1 on stairs or work platforms;   | safety check as             | After Every Use                    |
|           | Do not use the robot in a humid environment or on surfaces covered with fluid or gooey stuff                         | instructed on the           | Wipe the scrubber body with a      |
|           | Remove objects from the floor that could be accidentally pushed by the rotation of the brushes; keep hands and feet  | H&S training and            | clean dampened cloth. Do not       |
|           | away from the rotation of the brushes;   | induction program           | use corrosive cleaning agents      |
| 18.       | Never wash the machine with direct or pressurized jets of water or with corrosive substances                         | 5. Place cleaning           | when wiping, it is                 |
|           | Do not use flammable materials in the water tank   | signs if the robot is       | recommended to use neutral         |
| 20.       | Do not use the charger if it is wet  | leaving damp                | cleaning agents or water           |
|           | Always charge the robot <u>in a ventilated area</u> , where the <u>temperature does not exceed 30 °C</u>             | floors                      | • Charge in time when the battery  |
|           | Inspect area of work and access  | 6. Before cleaning          | is low                             |
| 23.       | Put away any wire or other objects on the ground to prevent the robot from being tripped or entangled.               | the robot, <mark>put</mark> | • Remove the disc brush for        |
| 24.       | Look for any new warnings  | gloves on                   | cleaning after each use            |
| 25.       | Watch out for leakage and slip hazards- Report it if you see it as well as leaving a do not use sign.                | 7.If you have been          |                                    |
| 26.       | Do not try and lift robot.   | trained to do so            | • If the disc brush is worn out,   |
| 27.       | Use WATER-BASED FIRE EXTINGUISHERS to put out the flames, and then use large quantities of water to cool down        | follow the                  | please replace with new disc       |
|           | the accidental battery to prevent re-ignition.   | <u>maintenance</u>          | brushes                            |
| 28.       | When operating the device, do not wear ties, scarves, or any accessories that could be entangled by the rotating     | guide and your              | Remove the squeegee for            |
|           | parts.   | training to clean           | cleaning after each use            |
| 29.       | Avoid touching any moving or rotating parts when device is working to prevent injuries.                              | the robot                   | • If the Squeegee is worn, broken, |
|           |  | 8.Look out for faults       | or deformed, which affects the     |
| Knowr     | n Hazards  | with the robot              | water-absorbing effect, it is      |
|           | Risk of Fire   | such as leakage or          | necessary to replace the strip     |
| 31.       | Risk of electric shocks  | an electrical smell         | with a new one                     |
| 32.       | Dangerous Atmospheres for battery charging   | Report to your line         |                                    |
| 33.       | Unprepared roadways or unsurfaced roads  | manager if you              |                                    |
|           | Cuts and manual handling injuries when changing pads, pad drives, squeegees, etc.                                    | notice an                   |                                    |
|           | Appliance tipping due to un-even floors  | abnormality                 |                                    |
|           | Collision with people walking past   | immediately.                |                                    |
|           | . Creating slip hazards if faulty  |                             |                                    |
| <i>J1</i> | . Crediting stip tricked as it reality   |                             |                                    |



### Monitoring and Reporting

- A visual check is to be completed every day before starting Machine. Use the machine ONLY IF the visual safety check is satisfactory.
- If abnormality or fault (s) are found, place signage and report to your line manager
- Reporting of any irregularity through e-mail along with phone call to <u>head office and Supervisor/area manager</u>

### Plant and equipment

• Professional miniature upright scrub and dry cleaner

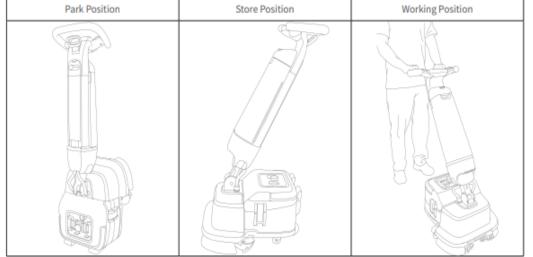
### Battery Charging & safety information

- Do not charge your robot using non-original chargers. If the charger is damaged, replace it
- In case of battery failure, remove the battery immediately and inform your line manager
- The machine and batteries should be stored at a temperature of -20° to 65° C and the relative humidity should be less than or equal to 40° C (93±3) %RH.
- Do not charge nearby flammable and explosive objects.
- Do not heat or burn the battery and charger.
- Ensure that the battery and charger are away from water and keep hands dry in operations.
- Do not compress, penetrate, or hit the charger to avoid battery damage.



### SUPPORTING IMAGES – Spec

| Specifications                 | Description                                     |                  |                          |  |  |  |  |
|--------------------------------|---|------------------|--------------------------|--|--|--|--|
|                                | Vertical State                                  | 49 x 53 x 120 cm | 19.29*20.87*47.24 inches |  |  |  |  |
| Product dimensions (L x W x H) | Store Position                                  | 49 x 35 x 127 cm | 19.29*13.78*50.00 inches |  |  |  |  |
| Product weight                 | 27 kg   |                  | 59.52 pounds             |  |  |  |  |
| Operating voltage              | DC 22-29.4 V                                    |                  |                          |  |  |  |  |
| Power input                    | AC 100V-240V,50/60H                             | lz               |                          |  |  |  |  |
| Power output                   | 29.4V, 8A                                       |                  |                          |  |  |  |  |
| Battery capacity               | 18 Ah   |                  |                          |  |  |  |  |
| Battery Life                   | 2.5 h   |                  |                          |  |  |  |  |
| Operation time of batteries    | Normal Mode: 70 mins                            |                  |                          |  |  |  |  |
| Operation time of batteries    | ECO Mode: 100 mins                              |                  |                          |  |  |  |  |
| Rated power                    | 380 W   |                  |                          |  |  |  |  |
| Brush speed                    | 350 rpm   |                  |                          |  |  |  |  |
| Productivity                   | 1100 - 1600 m <sup>2</sup> / h                  |                  | 11840-17222 ft²/h        |  |  |  |  |
| Working width                  | 44 cm   |                  | 17.32 inches             |  |  |  |  |
| Squeegee width                 | 49 cm   |                  | 19.29 inches             |  |  |  |  |
| Solution tank capacity         | 4 L   |                  | 1.06 Gal                 |  |  |  |  |
| Recovery tank capacity         | 4 L   |                  | 1.06 Gal                 |  |  |  |  |
| Noise level (SPL)              | Normal Mode: 76 dB (A)                          |                  |                          |  |  |  |  |
| Noise level (SPL)              | ECO Mode: 71 dB (A)                             |                  |                          |  |  |  |  |
| Wi-Fi                          | 2.4G Wi-Fi: 19.83 dBm                           |                  |                          |  |  |  |  |
| Charge on the machine          | Yes   |                  |                          |  |  |  |  |
| Intelligent functions          | Touch screen, liquid level detection, WiFi, APP |                  |                          |  |  |  |  |
| IP rating                      | IPX4  |                  |                          |  |  |  |  |





STEP 7 – RISK ASSESSMENT (Likelihood X Severity = Risk)

| CATEGORY                              | HAZARD   | POTENTIAL<br>HARM                                   | LIKELIH<br>OOD | Severity | Risk Before<br>Controls | Risk<br>After<br>Controls | COMMENTS  |
|---------------------------------------|--|---|----------------|----------|-------------------------|---------------------------|---|
| Operation of equipment                | Fire, / Shortcut<br>/electric shocks   | Burns, shock,                                       | 2              | 5        | 10                      | 5                         | <ul> <li>Employees are trained on the safe used of the Pudu SH1</li> <li>Weekly electrical safety inspection in place and documented by site supervisor and annually by area manager</li> <li>Visual inspection is in place before the operation</li> <li>Supervision is in place before and during the operation</li> <li>Reporting procedures are in place.</li> <li>Thermal protection is in place</li> <li>Operators are aware not to charge close to metal objects</li> <li>User needs to read and understand the user manual</li> <li>An operative without training cannot touch the Robot</li> <li>Self-charging- Employees do not have to plug in the robot manually</li> </ul> |
| Machine<br>preparation /<br>operation | Slip, trips and falls<br>due to uneven or<br>slippery surfaces<br>or obstacles on<br>the floor | Back injury<br>/bruises/cuts<br>Machinery<br>damage | 3              | 4        | 12                      | 4                         | <ul> <li>Visual check of the area</li> <li>Competent supervision of the robot is in place</li> <li>Employees cleaning the robot must follow the manual and be trained</li> <li>Reporting in place to watch for leakage from the machine</li> <li>Communication with the building management for the storage area arrangements</li> <li>Good housekeeping for the machinery storage area</li> </ul>  |
| Manual<br>Handling                    | Heavy<br>objects/bending   | Back injuries                                       | 3              | 3        | 9                       | 3                         | <ul> <li>Staff are to avoid manually moving the robot.</li> <li>Robot is programmed to move via phone app</li> <li>Staff training</li> <li>Toolbox programme</li> <li>Component supervision</li> <li>Site induction</li> </ul>  |
| Battery<br>charging                   | Accidental short<br>circuit,<br>overcharging,<br>submerge in<br>water                          | Burns, fire, shocks<br>Damage to<br>property        | 2              | 5        | 10                      | 5                         | <ul> <li>Only trained operatives allow to use the machinery</li> <li>Operatives are not allowed to dismount battery or compartments</li> <li>Robot cannot be charged or handled near sources of heat, flames or sparks</li> <li>Robot has smart technology to stop overcharging</li> <li>Visual check before commencing in place</li> <li>Operatives trained and instructed on the use of electric equipment</li> <li>Toolbox program in place</li> <li>Supervision and reporting of incidents</li> <li>Original charger</li> <li>Not to charge close to metal objects or liquids</li> <li>Self-charging in dock</li> </ul>   |



| Manual<br>handling<br>moving<br>parts  | handling and locks when operating the   |  | hing,<br>ring,<br>ng<br>nglement,<br>act, | 2  | 2   | 4  | 2                                | <ul> <li>Induction and training in place</li> <li>Manual handling toolbox</li> <li>Staff trained on the Reporting of dangerous occurrences and accidents</li> <li>Staff are aware they aren't allowed to move the robot themselves and can only report to the Supervisor / Area manager</li> <li>Employees trained to move the robot have been trained on correct manual handling techniques</li> </ul> |
|--|---|--|---|--|---|--|----------------------------------|---|
| Collision<br>with the<br>robot   | with the with robot                     |  | of falling<br>and<br>ing<br>nselves       | 3  | 3   | 9  | 3                                | <ul> <li>Robot has built-in sensors</li> <li>Robot used in open spaces and is easy to see</li> <li>Robot used in the evening when the building is almost empty (After working hours)</li> </ul>   |
| OVERALL RISK R   | OVERALL RISK RATING BEFORE CONTROL: 9.0 |  |   | Very<br>Low  | Low   | Medium   | High                             |   |
|  |   |  |   |  |   | ✓  |                                  |   |
| OVERALL RISK R   | OVERALL RISK RATING AFTER CONTROL: 3.7  |  | Very<br>Low                               | Low  | Medium  | High   |                                  |   |
|  |   |  |   | <b>✓</b>   |   |  |                                  |   |
| LIKELIHOOD  1. IMPROBABLE OCCURRENCE 2. REMOTED OCCURRENCE 3. REASONABLY PROBABLE OCCURRENCE 4. VERY LIKELY OCCURRENCE 5. ALMOST CERTAIN OCCURRENCE 5. MAJOR: Immidiate dar a wide scale and serious damage, etc.) |   |  |   | ng medical t<br>es resulting ir<br>or permane<br>ager exist, cap | reatment with temporary control disibility (e. pable of causi | n absence from 3<br>disibility (eg. fractu<br>g loss of limb, sig<br>ng death, loss or | ures) and ht) property damage on | INTERPRETATION  4 and below very Low risk = No further action, but ensure controls are maintained an review  5 to 8 Low risk = Risk Can be tolerated or for only short term. Plan introduction of meassures with a define time period  9 to 15 Medium Risk = Planned and introduce further control measures to mitigate the risk within a time scale  16 and Above = Stop activity and immediate action |